



Functional Reactive Programming

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Specification Languages for Verification

Mathematical Roots

- ▶ Formal *mathematical* description
- ▶ Provability
- ▶ "What" versus "How"



Concepts of Functional Programming

- ▶ Referential Transparency (No reassignment)
- ▶ Purity (No side effects)
- ▶ First Class or Higher Order Functions
- ▶ Recursion

Functional Programming Example

Quicksort

```
qsort :: (Ord a) => [a] -> [a]
qsort []      = []
qsort (x:xs) = qsort less ++ [x] ++ qsort more
               where less = filter (<x) xs
                     more = filter (>=x) xs
```



Side Effects

So:

Side effects are against the programming paradigm.

But:

Side effects are required for a program to interact with its environment or users.

Functional Reactive Animation

- ▶ Authors: Paul Hudak and Conal Elliott
- ▶ First appearance: International Conference of Functional Programming 1997
- ▶ Purpose: Creation of (interactive) animation
- ▶ Signals: Behaviours and Events; both first class
- ▶ Implementation: Embedded in Haskell, running on HUGS (Haskell User Gofer System)

Features

- ▶ **Time**: Is a Behaviour
- ▶ **liftn** : Maps n signals to one other via a function parameter
- ▶ **timeTransform**: Accelerates/Delays behaviours
- ▶ **integrate**: Integrates a numeric behaviour
- ▶ **untilB**: Switching of signals

Reactivity

Red-Green-Cycle

```
colorCycle t0 = red 'untilB' lbp t0 *=>  
  \t1 -> green 'untilB' lbp t1 *=>  
  \t2 -> colorCycle t2
```


Integration

Mouse-Follower

```
followMouseRate im t0 = move offset im
  where offset = integral rate t0
         rate = mouse t0 .-. pos
         pos = origin2 .+^ offset
```

$$s(t) = \int v(t)dt + s_0$$

Behaviour attempts

1. **data Behavior** a = **Behavior** (Time \rightarrow a)

Not efficient enough

2. **data Behavior** a = **Behavior**
(Time \rightarrow (a, **Behavior** a))

Sampling produces (simplified) new behaviour

3. **data Behavior** a = **Behavior**
(Time \rightarrow (a, **Behavior** a))
(|v| **Time** \rightarrow (|v| a, **Behavior** a))



Predicate

predicate (time * exp (4 * time) ==* 10) 0

Evaluates to true at an **infinitely** small time span

Interval Analysis

Remember:

$(|v| \text{ **Time** } \rightarrow (|v| \text{ **a**, **Behavior a** }))$

returns an interval of values the behaviour assumes in a certain time span.

Haskell is lazy

Only computes when the result is required

Advantages

- ▶ infinite data structures
- ▶ Spares unnecessary computation

Disadvantages

- ▶ time and space leaks
- ▶ Hard to predict resource requirements



Real Time FRP

- ▶ Authors: Zhanyong Wan, Walid Taha and Paul Hudak
- ▶ Purpose: Real Time Applications
- ▶ Implementation: As Intermediate Language



Properties for Real Time Development

- ▶ statically typed and type preserving
- ▶ signals are not first class
- ▶ bounded FRP term size
- ▶ constant time and space requirements for FRP commands

Features

1. **ext** is equivalent to **lift0** .
2. **let signal** $x = s1$ **in** $s2$ allows to access the current value of the first signal in an **ext** term forming the second signal
3. **delay** v s delays a signal by one tick. It displays v in the first tick.
4. $s1$ **switch on** $x = ev$ **in** $s2$ switches from $s1$ to $s2$ whenever event ev occurs. Starts out as $s1$.

Syntax

Definition

$$e ::= x \mid c \mid () \mid (e_1, e_2) \mid e_\perp \mid \perp \mid \lambda x. e \mid e_1 e_2 \mid \text{fix } x. e$$
$$v ::= c \mid () \mid (v_1, v_2) \mid v_\perp \mid \perp \mid \lambda x. e$$
$$s, ev ::= \text{input} \mid \text{time} \mid \text{ext } e \mid \text{delay } v \mid s \mid$$
$$\text{let signal } x = s_1 \text{ in } s_2 \mid s_1 \text{ switch on } x = ev \text{ in } s$$

Compiling FRP into RT-FRP

Lift

lift1 $e\ s \equiv$

let signal $x = s$ **in ext** $(e\ x)$

lift2 $e\ s1\ s2 \equiv$

let signal $x1 = s2$ **in**
 let signal $x2 = s2$ **in ext** $(e\ x1\ x2)$



Elm

- ▶ Author: Evan Czaplicki
- ▶ Purpose: GUIs for Web applications
- ▶ Implementation: Compiles into an intermediate language and then into JavaScript

Improvements over classic FRP

Classic FRP

- ▶ Continuous Signals
- ▶ Strict Event Ordering

Resulting Problems

- ▶ Needless Recomputation
- ▶ Global Delays

Solutions

- ▶ Only discrete Signals
- ▶ Memoization
- ▶ non Strict Event Ordering

Features

1. **lift** : Self explanatory
2. **async**: Marks independent code
3. **foldp**: It takes the current value of signal s and the accumulator a and feeds them to the function f . The result then replaces the accumulator. **foldp** f a s itself evaluates to a signal that contains all accumulator values.

Syntax

Definition

$$e ::= () | n | x | \lambda x : \eta. e | e_1 \ e_2 | e_1 \oplus \ e_2 |$$
$$\text{if } e_1 \ e_2 \ e_3 | \text{let } x = e_1 \ \text{in } e_2 | i |$$
$$\text{lift}_n \ e \ e_1 \ , \dots \ e_n | \text{foldp } e_1 \ e_2 \ e_3 |$$
$$\text{async } e$$
$$\tau ::= \text{unit} | \text{int} | \tau \rightarrow \tau'$$
$$\sigma ::= \text{signal } \tau | \tau \rightarrow \sigma | \sigma \rightarrow \sigma'$$
$$\eta ::= \tau | \sigma$$

Signals of Signals

lift (foldp (+) 0) signalOfSignals

Evaluating $\langle \langle 1,2,3,4,\dots \rangle, \langle 5,6,7,8,\dots \rangle, \dots \rangle$

Remembering Everything

$\langle \langle 1,3,6,10,\dots \rangle, \langle 5,11,18,26,\dots \rangle, \dots \rangle$

Evaluation only from the current time on

$\langle \langle 1,3 \rangle, \langle 7, 15,\dots \rangle, \dots \rangle$

Graph representation

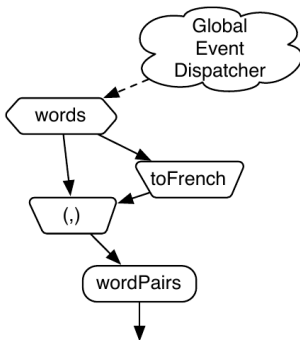


Figure: Program graph

Automaton

Definition

data Automaton a b =
 Step (a \rightarrow (Automaton a b, b))

Functions on Automaton

```
step : a -> Automaton a b
      -> (Automaton a b, b)
step input (Step f) = f input
```

```
run : Automaton a b -> b
     -> Signal a -> Signal b
```

```
run automaton base inputs =
  let step' input (Step f, _) = f input
  in lift snd (foldp step' (automaton,
    base) inputs)
```



”A Farewell to FRP”

Making signals unnecessary with The Elm Architecture

- ▶ Signals are hard to understand
- ▶ Signals are not used that much

Posted at the official website of Elm

Conclusion

Ideas of FRP are useful and it is flexible enough to suit a variety of applications, each approach to a different domain treats signals differently:

- ▶ Fran: First class behaviours and events
- ▶ RT-FRP: Only behaviours
- ▶ Elm: Only events

Event processing is key to most GUI frameworks

References I



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